

PHY221 Classical Physics **Essential equations**

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Harmonic oscillators

Newon's law $F = ma = m \frac{d^2x}{dt^2}$

Hooke's law $F = -kx$

$$\omega = \frac{2\pi}{T} = 2\pi f$$

- Simple harmonic oscillator

equation: $\frac{d^2x}{dt^2} + \omega_0^2 x = 0$

mass-spring: $\omega_0 = \sqrt{\frac{k}{m}}$

pendulum: $\omega_0 = \sqrt{\frac{g}{l}}$

solution: $x(t) = x_{\max} \cos(\omega_0 t + \phi)$

- Damped harmonic oscillator

equation: $\frac{d^2x}{dt^2} + 2\gamma \frac{dx}{dt} + \omega_0^2 x = 0$

$$\gamma = \frac{c}{2m}$$

solution for weak damping: $x(t) = x_{\max} e^{-\gamma t} \cos(\omega_d t + \phi)$

$$\omega_d = \sqrt{\omega_0^2 - \gamma^2}$$

critical damping when $\gamma^2 = \omega_0^2$

- Driven harmonic oscillator

equation: $\frac{d^2x}{dt^2} + 2\gamma \frac{dx}{dt} + \omega_0^2 x = \frac{F_0}{m} e^{i\omega t}$

solution: $x(t) = A(\omega) e^{i(\omega t - \phi(\omega))}$

Maximum when driving frequency ω equals the resonance frequency:

$$\omega_r = \sqrt{\omega_0^2 - \gamma^2}$$

- Quality factor

$$Q = \frac{A(\omega_r)}{A(0)} \approx \frac{\omega_0}{2\gamma}$$

$$Q = \pi N \quad \left(N \text{ oscillations for amplitude to decay to } \frac{1}{e} \right)$$

$$Q = \frac{\omega_r}{\Delta\omega_{\text{FWHM}}}$$

Waves

$$\text{wave equation: } \frac{\partial^2 f}{\partial t^2} = c^2 \frac{\partial^2 f}{\partial x^2}$$

$$\text{solution: } f(\phi) \text{ where } \phi = kx \pm \omega t$$

$$c = \lambda f \quad k = \frac{2\pi}{\lambda} \quad \omega = ck$$

$$\text{dispersion relation } \omega(k) = c(k)k$$

$$\text{phase velocity } c = \frac{\omega}{k}$$

$$\text{group velocity } v_G = \frac{d\omega}{dk}$$

$$\text{impedance } Z = c\rho$$

$$\text{reflection/transmission } r + t = 1$$

Fictitious forces

$$\text{Centrifugal force } \mathbf{F}'_{\text{cf}} = -m\boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r}')$$

$$\text{Coriolis force } \mathbf{F}'_{\text{cor}} = -2m\boldsymbol{\omega} \times \mathbf{v}'$$

Lagrangian mechanics

$$L = T - V$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_i} \right) = \frac{\partial L}{\partial q_i}$$

If $\frac{\partial L}{\partial q_i} = 0$ then q_i is cyclic/ignorable and $\frac{\partial L}{\partial \dot{q}_i}$ is a constant of motion.

$$\text{Translational kinetic energy } T = \frac{1}{2}mv^2$$

$$\text{Rotational kinetic energy } T = \frac{1}{2}I\omega^2$$

$$\text{Gravitational potential energy } V = -\frac{GM_1M_2}{r}$$